<u>G</u> E 🕀 D E T I C S INCORPORATED

GCP Free Photogrammetry

Precision in Motion. Geodetics is an Advanced Sensing and Navigation Company Based in the U.S.A.

Rotating Mounting for Horizontal/Vertical Mapping

- Image Time-tagging and Geotagging
- **Exterior Orientation Parameters (Omega, Phi, Kappa)**
- **Reduced Overlap**
- **Increase Mapping Coverage**
- **Single Crew Operation**
- Survey Grade Dual-Antenna Inertial Navigation
- Upgradeable to Integrate with the LiDAR

Geo-Photomap[™] GCP-Free Drone Photogrammetry System

Geo-Photomap integrates GPS/IMU with RGB imagery enabling GCP-free direct-georeferencing with significantly reduced side lap, resulting in more coverage in less time.



Vertical Structure Inspection



Corridor Mapping

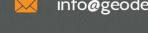


"One Click" Data Processing



Ready-to-Fly Package





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www.geodetics.com

Geo-Photomap[™]

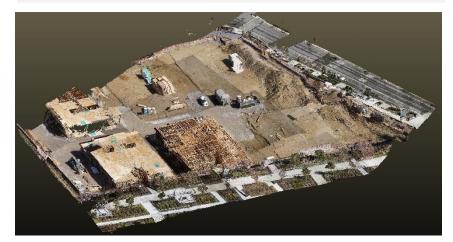
UAV Photogrammetry Payload

Parameter	
Size / Weight / Power	44 in ³ (5.5x4.0x2.0) 3.5 lbs.* / 10 – 30 VDC @ 2 Amps min.
Real-Time Data Output	Navigation solutions at up-to 125 Hz. available via Ethernet or RS-232
Data Recording/Logging	Navigation solutions, raw GPS, IMU and LiDAR point clouds

For more information about the Geo-MMS inertial unit, please check our website: <u>http://geodetics.com/product/geo-inav-tactical/</u> *Weight without mounting assembly. Total weight depends on system options and setup configuration.

ſ	Processing	Typical Position, Velocity, Acceleration, Attitude Accuracy (RMS)*						
	options	Position		Velocity,	Roll, Pitch	Heading		
				Acceleration		(boom separation)		
L		Horizontal	Vertical			1m	2m	
	L1/L2 SBAS	0.5m	1.5m	0.1 m/s, 0.15 m/s ²	0.1°	±0.26°	±0.08°	
	L1/L2 PPK	3cm	5cm	0.02 m/s, 0.1 m/s ²	0.05°			

*Accuracy is dependent upon GPS satellite system performance, ionospheric conditions, GPS blockage, data link and other factors



Classic UAV Photogrammetry with GCP; high overlap/sidelap

Geo-Photomap GCP-free; Low sidelap



	Classic UA\ togramme		Geo-Photomap Photogrammetry*						
Proces	er of image ssing time: 3 ap/Sidelap: 8	35 Hr	 Number of images: 200 Processing time: 3 Hr Overlap/Sidelap: 85%/40% 						
Average RMS on more than 20 check point[m]									
East	North	Up	East	North	Up				
-0.02	-0.06	-0.08	0.01	-0.06	-0.07				

*Sony A6000 camera (focal length: 16mm), AGL: 55m





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